WHISTLING: Wasp Behavior Inspired Stochastic Sampling

Vincent Cicirello and Stephen F. Smith

The Robotics Institute
Carnegie Mellon University
Pittsburgh PA 15213
{cicirello,sfs}@cs.cmu.edu

Carnegie Mellon



Introduction

- Question: How can we cover higher-valued points of solution-space in combinatorial domains efficiently?
- · Search heuristics can provide a basis
- · Heuristics are not infallible
- We must balance adherence to heuristic against possibility of missing better solutions
- Randomization as approach to hedging on this trade-off

THE ROBOTICS INSTITUTE

Dispatch Scheduling Policies

Local rules for prioritizing work on different resources and coordinating material flows

Examples: FIFO, WSPT, ATC

Advantages:

· Simple, robust control regime

Disadvantages:

- · Decisions tend to be myopic
- No one heuristic tends to dominate across varying production characteristics



Carnegie Mellon

Some Characteristics of Dispatch Heuristics

- Typically quite sensitive to parameter settings
 - Often tuned to individual problem instances during experimental evaluation
- Typically designed and validated under idealized modeling assumptions
 - Adapted to account for additional constraints

Research question: Can the performance of such decision rules be improved by adding randomness?



Amplifying Dispatch Heuristics

Starting assumption: We have a good heuristic, but its discriminatory power varies from context to context

Approach: Calibrate the degree of randomness in the heuristic's choice to the level of uncertainty in a given decision context

Some Related Ideas:

- Limited Discrepancy Search [Harvey & Ginsberg 95]
- Depth-Bounded Discrepancy Search [Walsh 97]
- Heuristic Equivalency [Gomes, Selman, & Kautz 98]
- Heuristic-Biased Stochastic Sampling [Bresina 96]
- Random-PCP [Oddi & Smith 97], Iterative Flattening [Cesta, Oddi, & Smith 99]



Carnegie Mellon

Limited Discrepancy Search (LDS) [Harvey & Ginsberg, 1995]

- · A systematic backtrack search procedure
- Iteration 0: follow search heuristic at each decision point
- Iteration j: systematically consider each solution trajectory with j discrepancies from the heuristic path
- Continue until feasible solution found or searchspace exhausted



Depth-bounded Discrepancy Search [Walsh, 1997]

- Assumes heuristic's advice most fallible near root of search-space
- An iterative-deepening variation of LDS
- Iteration j: Perform LDS restricting discrepancies to depth j of search-space
- Continue until feasible solution found or searchspace exhausted

THE ROBOTICS INSTITUTE

Carnegie Mellon

Iterative Sampling [Langley, 1992]

- At each decision point, choose a branch of the search space at random until a leaf-node is reached.
- If an infeasible solution is found, return to root of search space and iterate.
- If a feasible solution is found and if this solution is better than the best found so far, then replace the best found solution with this solution. Return to root and iterate.
- A rather naïve approach:
 - Assumes a large number of feasible solutions
 - · Assumes a large number of "good" solutions



Heuristic-Biased Stochastic Sampling [Bresina,1996]

- At each decision point, rank order the possible choices according to a search heuristic.
- Choose branch of search space randomly but biased according to a function of this ranking.
- E.g., choose branch b_i with probability:

$$\frac{bias(rank(b_i))}{\sum bias(rank(b_j))}$$

- · Continue as in Iterative Sampling.
- · Assumes a good ordering heuristic.



Carnegie Mellon

Our Approach: WHISTLING

- Motivation: heuristic more or less discriminating from context to context.
- Same basic idea as in HBSS, but decisions are biased according to a function of the heuristic value.
- E.g., choose branch b_i with probability:

$$\frac{bias(heuristic(b_i))}{\sum bias(heuristic(b_j))}$$

• Eliminates the O(n log n) ranking step of HBSS



Why "Wasp beHavior Inspired"?

- Algorithm's name related to "how" the stochastic decision is computed
- · Obvious method:
 - Pass one: compute $\sum bias(heuristic(b_i))$
 - Generate random number
 - Pass two: choose b_i with probability:

$$\frac{bias(heuristic(b_i))}{\sum bias(heuristic(b_j))}$$

Wasp analogy reduces this to a single pass



Carnegie Mellon

Wasp Behavior Model [Theraulaz et al., 1991]

- Each wasp of the colony has a force variable F_w
- · Any two wasps may engage in a dominance contest
- · Wasp 1 defeats wasp 2 with probability:

$$\frac{F_1^2}{F_1^2 + F_2^2}$$

- · Winner's force is increased; loser's force decreased
- · A social hierarchy formed over time
- Possible analogy between most dominant wasp and most "dominant" choice?



WHISTLING: Wasp beHavior Inspired STochastic sampLING

- At a decision point in the search:
 - Each choice represented by a "wasp"
 - Initial force of wasp i:

$$F_i = bias(heuristic(b_i))$$

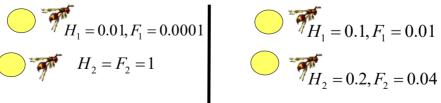
- Tournament of dominance contests
 - Wasp 0 competes against wasp 1
 - Winner's force F_w accumulates loser's force F_l
 - Loser drops out
 - Winner competes against wasp 2, ...



Carnegie Mellon

Illustrative Example

$$F_{w} = ATCS_{w}(t, l) = \frac{w_{j}}{p_{j}} \exp(-\frac{\max(d_{j} - p_{j} - t, 0)}{k_{1}\overline{p}}) \exp(-\frac{s_{lj}}{k_{2}\overline{s}})$$





$$P(W_2 \text{ winning}) = \frac{1}{1.0001} = 0.999$$
 $P(W_2 \text{ winning}) = \frac{0.04}{0.05} = 0.8$

$$H_1 = 0.1, F_1 = 0.01$$

$$H_2 = 0.2, F_2 = 0.04$$

$$P(W_2 \text{ winning}) = \frac{0.04}{0.05} = 0.8$$



A Competing Approach

- Heuristic-Biased Stochastic Sampling (HBSS) [Bresina, AAAI-96]
- Bias is based on rank ordering





$$H_2 = 1$$
 $H_1 = 0.01$
 $rank_2 = 1$ $rank_1 = 2$

$$\operatorname{rank}_2 = 1 \operatorname{rank}_1 = 2$$

$$P(\text{selecting } J_2) = \frac{1/1^2}{1/1^2 + 1/2^2} = 0.8$$
 $P(\text{selecting } J_2) = \frac{1/1^2}{1/1^2 + 1/2^2} = 0.8$





$$H_2 = 0.2$$
 $H_1 = 0.1$
rank₂ = 1 rank₁ = 2

$$rank_2 = 1 rank_1 = 2$$

$$P(\text{selecting } J_2) = \frac{1/1^2}{1/1^2 + 1/2^2} = 0.8$$



Carnegie Mellon

Computational Study

Experimental Design:

- Objective: Weighted tardiness
- Base heuristic: ATCS [Lee, Bhaskaran, and Pinedo 97]
- 120 problem instances
 - 60 jobs each, single machine
 - Varying degrees of due-date tightness, due-date range, and setup severity

Comparative analysis of Whistling and HBSS approaches

- Evaluation of a spectrum of bias functions for each approach
- 1, 10, and 100 restarts considered



Percentage Improvement over Deterministic ATCS Rule

| | Whistling | HBSS | Whistling | HBSS | Whistling | HBSS |
|--------------------|-----------|-------|-----------|-------|-----------|-------|
| # Restarts | 1 | 1 | 10 | 10 | 100 | 100 |
| Loose due-dates | 20.29 | 14.86 | 45.14 | 38.98 | 55.35 | 52.38 |
| Medium due-dates | 2.13 | 1.47 | 8.38 | 6.40 | 13.73 | 10.73 |
| Tight due-dates | 0.04 | 0.21 | 0.91 | 0.88 | 1.71 | 1.83 |
| Severe setups | 8.12 | 4.34 | 20.94 | 17.21 | 27.03 | 24.37 |
| Moderate setups | 6.86 | 6.69 | 15.35 | 13.63 | 20.16 | 18.93 |





- Same problem instances as in Whistling / HBSS comparison
- · Comparative analysis of Whistling, LDS, and DDS
 - 100 and 200 restarts considered for Whistling
 - LDS:
 - All single discrepancy solutions occurring in 1st four decisions (230)
 - All single discrepancy solutions (1770)
 - DDS: To depth 2 (3539)



Percentage Improvement over Deterministic ATCS Rule

| | Whistling | LDS | Whistling | LDS | DDS |
|------------------|-----------|-------|-----------|-------|-------|
| # Samples | 100 | 230 | 200 | 1770 | 3539 |
| Loose due-dates | 55.35 | 52.37 | 57.21 | 57.14 | 56.75 |
| Medium due-dates | 13.73 | 11.32 | 14.84 | 13.63 | 12.18 |
| Tight due-dates | 1.71 | 1.81 | 2.29 | 2.12 | 1.83 |
| Severe setups | 27.03 | 25.08 | 28.11 | 26.98 | 26.36 |
| Moderate setups | 20.16 | 18.59 | 21.45 | 21.61 | 20.82 |



Carnegie Mellon

CPU Time

| HBSS | HBSS | Whistling | Whistling | Whistling | LDS | LDS | DDS |
|--------|-------|-----------|-----------|-----------|------|------|-------|
| 10 | 100 | 10 | 100 | 200 | 230 | 1770 | 3539 |
| 1.59 s | 15.46 | 0.16 s | 1.50 s | 3.01 s | 1.46 | 6.04 | 20.94 |

·Note:

- •100 iterations of Whistling in same time as 10 iterations of HBSS
- •100 iterations of Whistling in same time as considering all 230 single discrepancy solutions in first 4 decisions
- •200 iterations of Whistling in half the time of considering all 1770 single discrepancy solutions
- •200 iterations of Whistling in a seventh of the time to consider the 3539 solutions of a DDS to depth 2



References

- [Bresina 96] J. Bresina. Heuristic-biased stochastic sampling. In *Proc. 13th Nat. Conf. AI*, 1996.
- [Cesta, Oddi, & Smith 99] A. Cesta, A. Oddi, and S. Smith. An iterative sampling procedure for resource constrained project scheduling with time windows. In Proc. 16th IJCAI, 1999.
- [Gomes, Selman, & Kautz 98] C. Gomes, B. Selman, and H. Kautz. Boosting combinatorial search through randomization. In *Proc.* 15th Nat. Conf. AI, 1998.
- [Harvey & Ginsberg 95] W. Harvey and M. Ginsberg. Limited discrepancy search. In ${\it Proc.}~14^{th}~IJCAI,$ 1995.
- [Langley 92] P. Langley. Systematic and nonsystematic search strategies. In *Proc.* 1st AIPS, 1992.
- [Oddi & Smith 97] A. Oddi and S. Smith. Stochastic procedures for generating feasible schedules. In *Proc.* 14th Nat. Conf. AI, 1997.
- [Theraulaz et al. 91] G. Theraulaz, S. Goss, J. Gervet, and J. Deneubourg. Task differentiation in polistes wasp colonies: a model for self-organizing groups of robots. In *Proc. 1st Int. Conf. On Simulation of Adaptive Behavior*, 1991.
- [Walsh 97] T. Walsh. Depth-bounded discrepancy search. In Proc. 15th IJCAI, 1997.

